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ORDERING CODE

REM

Miniaturized electronic regulator in Undecal type container



Double solenoid



Asymmetrical ramp



Maximum output

current I $_{MAX.}$ (JU variant) $\mathbf{X} = 0.88 \text{ A } (0.80 \text{ A})$

Y = 1.76 A (1.20 A)

Z = 2.8 A



Input reference (V) see note (*) below

 $2 = -2 \div +2 \text{ V}$

 $5 = -5 \div +5 \text{ V}$

0 ÷ +5 V

 $0 = -10 \div +10 \text{ V}$

 $A = -20mA \div +20mA$

0 ÷ +20mA

Frequency Dither

1 = 100 Hz (standard, JU var.)

2 = 330 Hz

G

Minimum initial current can only be adjusted in steps

00 = No variant

4

Serial No.

(*) If the input reference is a current signal (mA) the regulator has to be pre-setted in the factory.

mark with reference to the electromagnetic compatibility.

European norms:

- EN61000-6-2 Generic standards. Immunity for industrial environments:
- EN61000-6-3 Generic standards. Emission standard for residential, commercial and light-industrial environments.

Product in accordance with RoHS 2011/65/UE Europe Directive.

REMDRA... TYPE ELECTRONIC REGULATORS **DOUBLE SOLENOID PROPORTIONAL CONTROL VALVES**

The electronic control card type REMDRA has been designed to drive the double solenoid proportional valves series "XD.*.C...and XDP.3.C" without integral position transducer. The control card is enclosed in an "UNDECAL" type housing, a typical relay mounting standard. The output stage operates on the pulse width modulation principle (P.W.M.) and is provided with current feedback in order to obtain a solenoid output current proportional to the reference input signal.

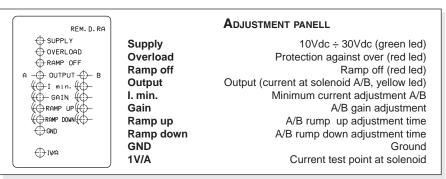
Output short circuit and supply polarity inversion protection is provided. Gain, minimum current and rise and fall ramp time adjustments are possible through the corresponding front panel trimming potentiometers, while the output current to the solenoid can be measured via the Valve Current test points, and the ramps can be excluded.

The product incorporates a serial interface for adjustment of parameters.

Pay attention please: electronic regulators must be used in dampness and water protected places.

Manuals and software

The user and installation manual, the manual for variants DJ/JU and the software DG are available on "products" section of www.brevinifluidpower.com website.

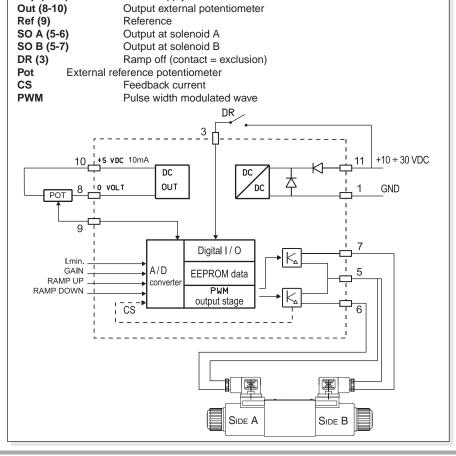


If any field is missing from the ordering code the standard setting is as follows:

- Input ref. = -5 ÷ +5V
- Dither = 100Hz
- $-I_{max.} = 0.8A$

Sup (1-11)

ELECTRICAL CIRCUIT AND CONNECTIONS Power supply





y

ELECTRONIC REGULATORS DOUBLE SOLENOID PROPORTIONAL CONTROL VALVES

Power supply	10 ÷ 30 VDC			
Maximum supply voltage	36 V			
Power absorption	40 W			
Current output setting by dip switches	Imax = 2.8A Imax = 1.76A Imax = 0.88A			
External potentiometer supply output short circuit protected	+5V I.max.10mA			
Reference input signal setting by dip switches	-2V ÷ +2V -5V ÷ +5V -10V ÷ +10V -20A ÷ +20mA (*)			
Signal input reference (pin n° 9) setting by dip switches	0V ÷ +5V 0 ÷ +20mA (*)			
Polarization current adjustment	Imin = 0 ÷ 50% Imax			
Current gain adjustment	50% ÷ 100% Imax			
Ramp time adjustment	0 ÷ 20 sec			
Ambient operating temperature	-20 ÷ +70°C			
Current test point	1 Volt = 1 Ampere			
Weight	0.120 Kg			

(*) For the current signal (mA) the regulator has to be pre-setted in the factory.

REMDRA... Instructions for use

CALIBRATION PROCEDURE

Connect the card in the proper way followingthe next page "Typical connections" but without powering it. Turn completely anticlockwise (20 turns about) the trimming potentiometers of Minimu Current (I_{\min}) and Ramp Time (Ramp-up and Rampdown), and position the reference potentiometer on zero. Before powering the card, ensure that any unforeseen hydraulic system movement cannot cause material damage or injury to people. Power now the card; the green LED should light up

Two channel minimum current (I $_{\mbox{\tiny MIN}}$) adjustment (dead band)

Set the reference signal of approx. Vref +150mV. Than turn clockwise the trimmer until an actuator movement can be visually detected (A channel Output LED lights up). Than turn the same trimmer anticlockwise until the movement stops. Repeat the I_{min} calibration for the other channel B.Set the reference signal of approx. Vref -150mV (B channel Output LED lights up).

GAIN ADJUSTMENT

Turn first the ramp time trimming potentiometers (RAMP UP) clockwise by at least 10 turns, if the system could be damaged by a too fast solenoid operation (evaluate the application carefully). The maximum actuator speed can now be adjusted. Turn the reference signal to the maximum positive setting value and rotate slowly the gain trimming potentiometer (GAIN) until the maximum required speed is obtained. The speed can now be varied by moving the potentiometer lever. Repeat the above operations for the other channel after turning the reference signal to the maximum negatif value.

RAMP TIME ADJUSTMENT

The ramp time is the time taken to pass from the minimum to the maximum current value, and vice versa. It's adjustable from a minimum of 0s up to a maximum of 20s (to reach the maximum current value setted) separately for channel A and B. Turning clockwise the trimming potentiometer, the ramp time increases.

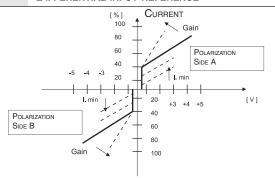
Notes

- 1) The ramp fall time affects the actuator stop position. Moving the reference potentiometer to zero Volt, the actuator goes on moving till the setted ramp time is elapsed. Therefore it's necessary to adjust it properly.
- 2) When the overload red LED lights up, it will be necessary to switch off the power to the card, switching it on again after having eliminated the cause of overload.

SIGNALS INPUT REFERENCE

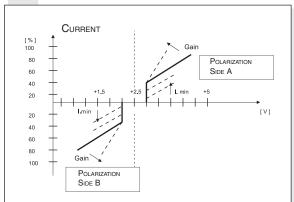
The REMD can recive two kinds of command signal inputs, differential input (non inverting, inverting voltage $-5V \div +5V$), or positive voltage $(0V \div +5V)$.

DIFFERENTIAL INPUT REFERENCE



For being able to command a proportional valve double solenoid with a differential input command voltage in income at contact 9 of REMD is necessary not to connect the contact 10 of REMD.

Positive input reference



For being able to command a proportional valve double solenoid with a positive command voltage in income at contact 9 of REMD is necessary to connect the contact 10 of REMD a resistive load:

- potentiometer (minimum 1000, max 5000 Ohm) [with external potentiometer command signal, pin n° 9]
- resistor (minimum 1000, max 5000 Ohm) [with external reference value generator, e.g. by a PLC , pin n° 9].

ELECTRONIC REGULATORS DOUBLE SOLENOID PROPORTIONAL CONTROL VALVES

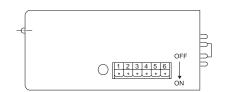
REMDRA... DIP SWITCHE TABLE

Six miniature switches are mounted internally on one of the REM sides. The REM configuration to suit any particular application can be implemented by setting these switches. PWM frequency (100 to 330 Hz), reference voltage range and maximum current (I_{max}) can thus be adjusted.

For our proportional valves are recommended the following settings:

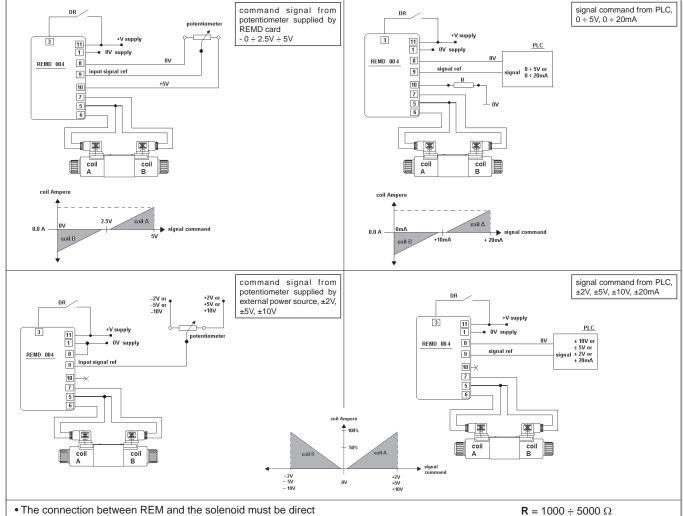
G	XD3C	DITHER =100Hz	$I_{max} = 2.35A$ with 9V coils
G	XDP3C	DITHER =100Hz	$I_{\text{max.}}^{\text{max.}} = 2.35A \text{ with 9V coils}$
G	XD2C	DITHER =100Hz	$I_{max} = 1.4A$ with 12V coils
G	XD3C	DITHER =100Hz	$I_{max} = 1.76A$ with 12V coils
G	XDP5C	DITHER =100Hz	$I_{max} = 2.5A$ with 12V coils
G	XDP3C	DITHER =100Hz	$I_{max} = 1.76A$ with 12V coils
G	XD2C	DITHER =100Hz	$I_{max} = 0.7A$ with 24V coils
G	XD3C	DITHER =100Hz	$I_{max} = 0.88A$ with 24V coils
G	XDP5C	DITHER =100Hz	$I_{max} = 1.25A$ with 24V coils
G	XDP3C	DITHER =100Hz	$I_{\text{max.}}^{\text{max.}} = 0.88A \text{ with 24V coils}$

For the version with reference signal in current it needs to be preset in-factory.



Function DITHER		l min	Input ref.					I.max.				
DIP sw	100 Hz	330 Hz	G	-10÷10 V	-5÷5 V		-20mA ÷20mA		0 ÷20mA	2.8 A	1.76 A	0.88 A
1	OFF	ON										
2			ON									
3				OFF	ON	OFF	ON	ON	ON			
4				OFF	OFF	ON	OFF	OFF	OFF			
5										OFF	ON	OFF
6										OFF	OFF	ON

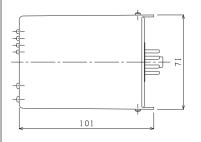
TYPICAL CONNECTIONS

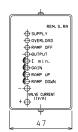


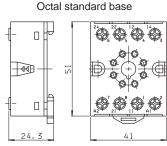
- The common one of return to proportional solenoid must not' be shared between other valve connections or electrical equipment worker.

POT = $1000 \div 5000 \Omega$

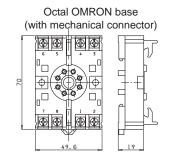






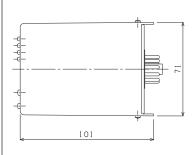


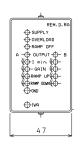
Ordering code X30800000

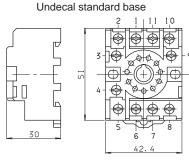


Ordering code X30800004

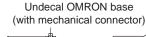
OVERALL DIMENSION AND MOUNTING BASES ON DIN GUIDES FOR REMDRA...

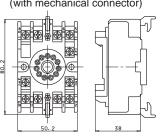






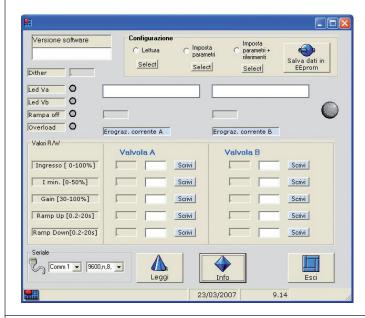
Ordering code X30900000





Ordering code X30900004

DG SOFTWARE



DG program for the digital adjustment of the parameters of the REMS and REMD boards.

DG program for the digital adjustment of the parameters of the REMS and REMD boards.

The program is used to store (the settings are cancelled when the REM board is switched off) the following parameters:

- Minimum current
- Upward current ramp
- Upward current ramp
- Downward current ramp

Italian/English version: purchase order code P35150003.

NB: the DG software can be used with all the REMS and REMD boards that have a TTL connector (production commencement year 2008).

SERIAL CABLE RS232/TTL



Ordering code VE0110001



REM connecting at computer with serial cable.

Motion Systems